

CBMS Lecture 6

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Multivariate spatial modeling

- ▶ Point-referenced spatial data often come as multivariate measurements at each location
- ▶ Examples:
 - ▶ Environmental monitoring stations yield measurements on ozone, NO, CO, PM_{2.5}, etc.
 - ▶ In atmospheric modeling at a given site we observe surface temperature, precipitation and wind speed
 - ▶ At a monitoring site we observe precipitation, wet sulfate deposition, wet nitrate deposition
 - ▶ At locations in a forest, we observe tree growth, soil moisture, light availability, climate variables
 - ▶ In real estate modeling for a commercial property we observe selling price and total rental income
- ▶ We anticipate dependence between measurements
 - ▶ at a particular location
 - ▶ across locations

Basic issues

- ▶ $\mathbf{Y}(\mathbf{s})$ denotes a $p \times 1$ vector of random variables at \mathbf{s}
- ▶ We seek to model $\mathbf{Y}(\mathbf{s}) : \mathbf{s} \in D$, again specifying finite dimensional distributions, e.g., for $\mathbf{Y} = (\mathbf{Y}(\mathbf{s}_1), \dots, \mathbf{Y}(\mathbf{s}_n))$
- ▶ *Crucial object*: the cross-covariance

$$C(\mathbf{s}, \mathbf{s}') = \text{Cov}(\mathbf{Y}(\mathbf{s}), \mathbf{Y}(\mathbf{s}'))$$

a $p \times p$ matrix that need not be symmetric, i.e.,
 $\text{cov}(Y_j(\mathbf{s}), Y_{j'}(\mathbf{s}'))$ need not equal $\text{cov}(Y_{j'}(\mathbf{s}), Y_j(\mathbf{s}'))$

- ▶ $C(\mathbf{s}, \mathbf{s}')$ is not positive definite except in a limiting sense:
 $C(\mathbf{s}, \mathbf{s})$ is the covariance matrix associated with $\mathbf{Y}(\mathbf{s})$.
- ▶ Our primary focus: Gaussian processes and valid specification for $C(\mathbf{s}, \mathbf{s}')$ to overlay

Separable models

- ▶ A common specification is the separable model

$$C(\mathbf{s}, \mathbf{s}') = \rho(\mathbf{s}, \mathbf{s}') \cdot T$$

where ρ is a valid (univariate) correlation function and T is a $p \times p$ positive definite matrix

- ▶ T is the non-spatial or “local” covariance matrix
- ▶ ρ controls spatial association based upon proximity
- ▶ Easy to verify that $\Sigma_{\mathbf{Y}} = H \otimes T$, where $H_{ij} = \rho(\mathbf{s}_i, \mathbf{s}_j)$ and \otimes is the Kronecker product.
 - ▶ $\Sigma_{\mathbf{Y}}$ is positive definite since H and T are
 - ▶ $\Sigma_{\mathbf{Y}}$ is convenient since $|\Sigma_{\mathbf{Y}}| = |H|^p |T|^n$ and $\Sigma_{\mathbf{Y}}^{-1} = H^{-1} \otimes T^{-1}$.

Application: Bivariate spatial regression

- ▶ A single covariate $X(\mathbf{s})$ and a univariate response $Y(\mathbf{s})$
- ▶ Treat this as a bivariate process. (WHY?)

$$\mathbf{Z}(\mathbf{s}) = \begin{pmatrix} X(\mathbf{s}) \\ Y(\mathbf{s}) \end{pmatrix} \sim N(\boldsymbol{\mu}(\mathbf{s}), T)$$

- ▶ Simplifying assumptions:
 - ▶ Separable cross-covariance for $\mathbf{Z}(\mathbf{s})$
 - ▶ $\boldsymbol{\mu}(\mathbf{s}) = (\mu_1, \mu_2)$, i.e., constant means.
- ▶ Then, $p(Y(\mathbf{s})|X(\mathbf{s})) = N(\beta_0 + \beta_1 X(\mathbf{s}), \sigma^2)$ where:

$$\beta_0 = \mu_2 - \frac{T_{12}}{T_{11}}\mu_1, \quad \beta_1 = \frac{T_{12}}{T_{11}}, \quad \text{and} \quad \sigma^2 = T_{22} - \frac{T_{12}^2}{T_{11}}$$

- ▶ Regression model parameters are functions of process model parameters

Bivariate spatial regression (cont'd)

- ▶ Rearrangement of the components of \mathbf{Z} to $\tilde{\mathbf{Z}} = (X(\mathbf{s}_1), X(\mathbf{s}_2), \dots, X(\mathbf{s}_n), Y(\mathbf{s}_1), Y(\mathbf{s}_2), \dots, Y(\mathbf{s}_n))'$ yields

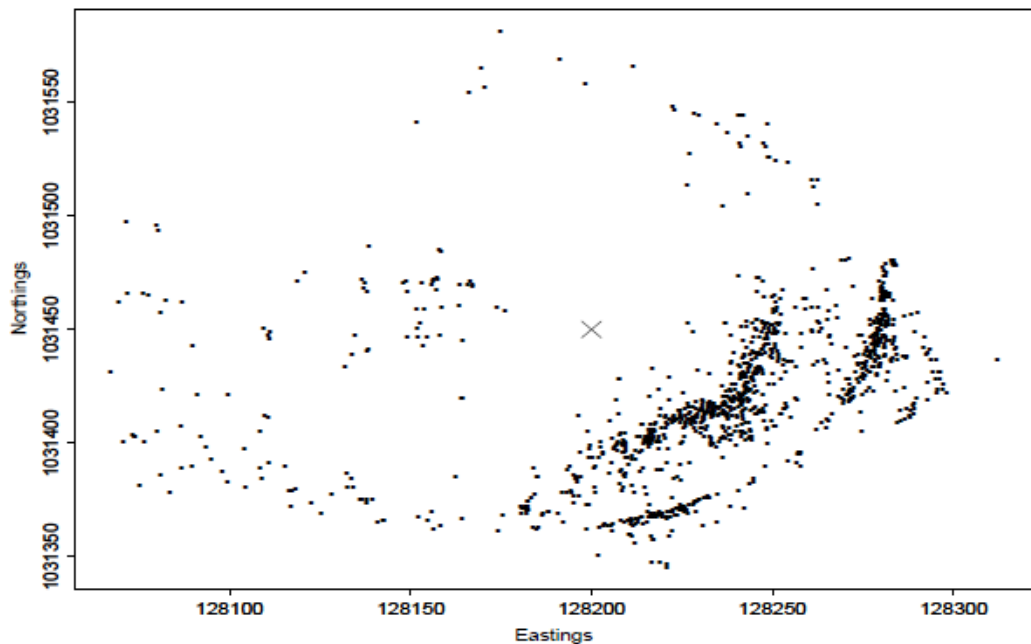
$$\begin{pmatrix} \mathbf{X} \\ \mathbf{Y} \end{pmatrix} \sim N \left(\begin{pmatrix} \mu_1 \mathbf{1} \\ \mu_2 \mathbf{1} \end{pmatrix}, T \otimes H(\phi) \right),$$

- ▶ Priors: Wishart for T^{-1} , vague but proper normal for (μ_1, μ_2) , discrete prior for ϕ
- ▶ Full conditionals for Gibbs sampler: again Wishart for T^{-1} , bivariate normal for (μ_1, μ_2) ; sampling from a discrete distribution for ϕ or perhaps a uniform on $(0, .5\max \text{ dist})$

Dew-shrub data example

- ▶ 1129 locations with UTM coordinates
- ▶ $Y(\mathbf{s})$: shrub density at location \mathbf{s}
- ▶ $X(\mathbf{s})$: Dew duration at location \mathbf{s}
- ▶ Illustrative analysis assuming separability and an exponential correlation function, $\rho(h; \phi) = e^{-\phi h}$
- ▶ Conjugate priors for $\boldsymbol{\mu}$, T as above; prior for ϕ has infinite variance and suggests a range $(3/\phi)$ of 125 km, roughly half the maximum pairwise distance in the region
- ▶ $(\mu_1, \mu_2, T_{11}, T_{12}, T_{22})$ updated directly; ϕ updated via Metropolis
- ▶ Posterior samples of $(\beta_0, \beta_1, \sigma^2)$ from posterior samples of process parameters

Sites yielding dew and shrub data



Parameter estimation, dew-shrub data

Parameter	2.5%	50%	97.5%
μ_1	73.12	73.89	74.67
μ_2	5.20	5.38	5.572
T_{11}	95.10	105.22	117.69
T_{12}	-4.46	-2.42	-0.53
T_{22}	5.56	6.19	6.91
ϕ	0.01	0.03	0.21
β_0	5.72	7.08	8.46
β_1	-0.04	-0.02	-0.01
σ^2	5.58	6.22	6.93
$T_{12}/\sqrt{T_{11}T_{22}}$	-0.17	-0.10	-0.02

⇒ Surprising - a significant negative association between dew duration and shrub density!

Benefits and limitations of separability

- ▶ Benefits:
 - ▶ Easy interpretation (decomposition of variance structure)
 - ▶ Substantial computational benefits
- ▶ Limitations:
 - ▶ Symmetry in cross-covariance matrix (not so serious)
 - ▶ Imposes same spatial range for every component (more serious, only one correlation function)
- ▶ a proposed solution
 - ▶ Coregionalization models

An simple nonseparable example

- ▶ The delay effect or pure offset model
- ▶ Define $\mathbf{Y}(\mathbf{s})$ to be two-dimensional such that $Y_2(\mathbf{s}) = Y_1(\mathbf{s} + \boldsymbol{\lambda})$. $\boldsymbol{\lambda}$ is a *delay* vector
- ▶ Cross covariance matrix is

$$\begin{pmatrix} \sigma^2 \rho(h) & \sigma^2 \rho(h + \lambda) \\ \sigma^2 \rho(-h + \lambda) & \sigma^2 \rho(h) \end{pmatrix}$$

- ▶ Here ρ is valid
- ▶ Can add a nugget, i.e., define $Y_2(\mathbf{s}) = Y_1(\mathbf{s} + \boldsymbol{\lambda}) + \epsilon(\mathbf{s})$
- ▶ Potential application to exposures driven by wind direction

Linear Model of Coregionalization

- ▶ For point referenced data, $\mathbf{Y}(\mathbf{s}) = A\mathbf{w}(\mathbf{s})$ where $\mathbf{w}(\mathbf{s}) = (w_1(\mathbf{s}), w_2(\mathbf{s}), \dots, w_p(\mathbf{s}))$
- ▶ p independent spatial processes with stationary correlation functions $\rho_j(\mathbf{s} - \mathbf{s}'), j = 1, 2, \dots, p$
- ▶ If $\rho_j = \rho$ for all $j \iff$ separable case with $AA' = T$
- ▶ In general, the cross covariance matrix is (with \mathbf{a}_j being the columns of A)

$$C(\mathbf{s} - \mathbf{s}') = \sum_{j=1}^p \rho_j(\mathbf{s} - \mathbf{s}') \mathbf{a}_j \mathbf{a}_j'$$

- ▶ Approach is “constructive” so $C(\mathbf{s} - \mathbf{s}')$ immediately valid, still stationary, and provides a distinct covariance function for each component

Linear Model of Coregionalization

- ▶ More general: $\mathbf{Y}(\mathbf{s}) = A(\mathbf{s})\mathbf{w}(\mathbf{s})$.
A spatially varying LMC!
- ▶ model $A(\mathbf{s}) \Leftrightarrow$ model $T(\mathbf{s}) = A(\mathbf{s})A'(\mathbf{s})$
- ▶ Possibilities for $T(\mathbf{s})$:
 - ▶ $T(\mathbf{s}) = g(X(\mathbf{s})) \times T$
 - ▶ $T(\mathbf{s})$ is a spatial process (e.g., $T^{-1}(\mathbf{s})$ is a spatial Wishart process)
- ▶ Computationally demanding

cont.

- ▶ Specification of A
- ▶ $p \times p$ entries in A but, since $A \Leftrightarrow T$, only require $\frac{p(p+1)}{2}$ parameters. For convenience, we often take A to be lower triangular.
- ▶ Given ϕ_1, \dots, ϕ_p , the cross covariance matrix is symmetric, regardless of A .
- ▶ Number of parameters in the model $\frac{p(p+1)}{2} + pm$ where m is the dimension of ϕ_j , i.e., number of parameters in the individual correlation functions.
- ▶ With $p = 2$, we have 3 parameters in A and, using an exponential covariance function, $m = 2$ decay parameters

cont.

- ▶ The one-to-one relationship between T and lower triangular A is standard.
- ▶ When $p = 2$ we have

$$a_{11} = \sqrt{T_{11}}, \quad a_{21} = \frac{T_{12}}{\sqrt{T_{11}}}, \quad a_{22} = \sqrt{T_{22} - \frac{T_{12}^2}{T_{11}}}$$

- ▶ When $p=3$ we add

$$a_{31} = \frac{T_{13}}{\sqrt{T_{11}}}, \quad a_{32} = \frac{T_{11} T_{23} - T_{12} T_{13}}{T_{11}(T_{11} T_{22} - T_{12}^2)}$$

and $a_{33} = \sqrt{T_{33} - \frac{T_{13}^2}{T_{11}} - \frac{(T_{11} T_{23} - T_{12} T_{13})^2}{T_{11}(T_{11} T_{22} - T_{12}^2)}}$

cont.

- ▶ More explicitly

$$\begin{pmatrix} Y_1(\mathbf{s}) \\ Y_2(\mathbf{s}) \\ \vdots \\ Y_j(\mathbf{s}) \\ \vdots \\ Y_p(\mathbf{s}) \end{pmatrix} = \begin{pmatrix} a_{11}w_1(\mathbf{s}) \\ a_{21}w_1(\mathbf{s}) + a_{22}w_2(\mathbf{s}) \\ \vdots \\ \sum_{l=1}^j a_{jl}w_l(\mathbf{s}) \\ \vdots \\ \sum_{l=1}^p a_{jl}w_l(\mathbf{s}) \end{pmatrix}.$$

- ▶ $\mathbf{Y}(\mathbf{s})$ is stationary, has a symmetric cross-covariance matrix, with a *different* variance and, if the $\rho(\cdot; \phi_j)$'s are isotropic, a *different* range for each component of $\mathbf{Y}(\mathbf{s})$.

General Multivariate Spatial Model

- ▶ So, we arrive at the model

$$\mathbf{Y}(\mathbf{s}) = \boldsymbol{\mu}(\mathbf{s}) + \mathbf{v}(\mathbf{s}) + \boldsymbol{\epsilon}(\mathbf{s})$$

with

- ▶ $\boldsymbol{\epsilon}(\mathbf{s}) \sim N(0, D_\epsilon)$, $(D_\epsilon)_{jj} = \tau_j^2$.
- ▶ $\mathbf{v}(\mathbf{s}) = A\mathbf{w}(\mathbf{s})$ following previous specification
- ▶ $w_j(\mathbf{s})$ are mean 0 Gaussian processes with individual correlation functions.
- ▶ $\boldsymbol{\mu}(\mathbf{s})$ arises from $\mu_j(\mathbf{s}) = \mathbf{X}_j^T(\mathbf{s})\boldsymbol{\beta}_j$.

A useful example

- ▶ Spatially varying coefficient models (Gelfand et al., 2003)
- ▶ Model $Y(\mathbf{s}) = \mathbf{X}(\mathbf{s})^T \boldsymbol{\beta}(\mathbf{s}) + \epsilon(\mathbf{s})$.
- ▶ Here $Y(\mathbf{s})$ is univariate. The multivariate process is for $\boldsymbol{\beta}(\mathbf{s})$. Use coregionalization here.
- ▶ For $p = 2$, with $\mathbf{X}(\mathbf{s})$ having a column of “1”'s, we obtain $\beta_0(\mathbf{s}) + X(\mathbf{s})\beta_1(\mathbf{s})$
- ▶ Spatially varying intercept (like a spatial random effect) and a spatially varying slope.
- ▶ Analogous to longitudinal growth curve models
- ▶ A very rich class of *nonlinear* models
- ▶ Infer about the multivariate process is for $\boldsymbol{\beta}(\mathbf{s})$ while only observing the univariate $Y(\mathbf{s})$ process

Hierarchical Model

- ▶ 1st stage:

$$\mathbf{Y}(\mathbf{s}_i) | \{\beta_j\}, \{\mathbf{v}(\mathbf{s}_i)\}, D_\epsilon \sim N(\boldsymbol{\mu}(\mathbf{s}_i) + \mathbf{v}(\mathbf{s}_i), D_\epsilon).$$

- ▶ 2nd stage:

$$\mathbf{v} = \begin{pmatrix} \mathbf{v}(\mathbf{s}_1) \\ \vdots \\ \mathbf{v}(\mathbf{s}_n) \end{pmatrix} \sim N(\mathbf{0}, \sum_{j=1}^p \mathbf{R}_j \otimes \mathbf{T}_j),$$

$\mathbf{Y}(\mathbf{s}_i)$ into \mathbf{Y} , $\boldsymbol{\mu}(\mathbf{s}_i)$ into $\boldsymbol{\mu}$, marginalize over \mathbf{v}

$$f(\mathbf{Y} | \{\beta_j\}, D_\epsilon, \{\rho_j\}, T) = N\left(\boldsymbol{\mu}, \sum_{j=1}^p (H_j \otimes T_j) + I_{n \times n} \otimes D_\epsilon\right).$$

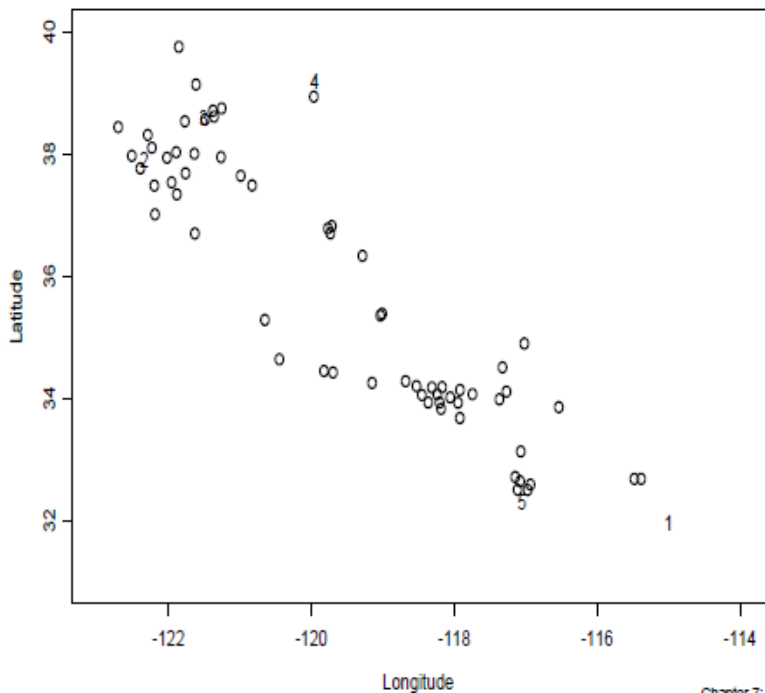
- ▶ 3rd stage: Priors on $\{\beta_j\}$, $\{\tau_j^2\}$, T and the parameters of the ρ_j .

California Pollution Data Example

- ▶ From the California Air Resources Board. Available for download at <http://www.arb.ca.gov/aqd/aqcdcd/aqdcdd1d.htm>.
- ▶ Daily average of Carbon Monoxide (CO), Nitric Oxide (NO) and Nitrogen dioxide (NO₂) based on hourly measurements on July, 6th, 1999 → **68 sites**.
- ▶ The observed correlations between these pollutants range from 0.46 (CO and NO) to 0.77 (NO and NO₂).
- ▶ Use the logarithm of the daily average of each of these variables.
- ▶ No information on covariates, such as temperature or wind directions, at these gauged sites.

Monitoring stations

Location of the 63 monitoring stations used to fit the model and the 5 used for prediction of NO_2



A model specification

- ▶ Can specify coregionalization model sequentially
- ▶ We anticipate smooth exposure surfaces so only spatial random effects, no nuggets
- ▶ The model:

$$CO(\mathbf{s}) = \mu_1 + \sigma_1 \tilde{w}_1(\mathbf{s})$$

$$NO(\mathbf{s})|CO(\mathbf{s}) = \mu_2 + \alpha CO(\mathbf{s}) + \sigma_2 \tilde{w}_2(\mathbf{s})$$

$$NO_2(\mathbf{s})|CO(\mathbf{s}), NO(\mathbf{s}) = \mu_3 + \gamma CO(\mathbf{s}) +$$

$$\beta NO(\mathbf{s}) + \sigma_3 \tilde{w}_3(\mathbf{s}),$$

with $\tilde{w}_j(\mathbf{s}) \sim GP(0, \rho_j)$ and

$$\rho_j = \exp\{-\psi_j \|\mathbf{s} - \mathbf{s}'\|\}$$

Prior specifications

$$\mu_1 \sim N(0, 5), \mu_2 \sim N(0, 5), \mu_3 \sim N(0, 5)$$

$$\alpha \sim N(0, 5), \gamma \sim N(0, 0.2), \beta \sim N(0, 0.2)$$

$$\sigma_1^2 \sim IG(5, 0.35 * 4), \sigma_2^2 \sim IG(5, 0.52 * 4), \\ \sigma_3^2 \sim IG(5, 0.13 * 4),$$

$$\psi_1 \sim Ga(0.6, 1), \psi_2 \sim Ga(0.6, 1), \\ \psi_3 \sim Ga(0.6, 1).$$

$p(\psi_j)$ based on $\psi = 3/\text{range}$ and $\text{range} = .5\text{max dist}$

Posterior Summaries

Posterior Summaries for CO (1), NO (2) and NO₂ (3).

Parameter	Mean	2.50%	Median	97.50%
α	0.296	0.045	0.292	0.553
β	0.302	0.190	0.301	0.413
γ	0.198	0.082	0.199	0.314
μ_1	-0.922	-1.135	-0.921	-0.710
μ_2	-5.015	-5.504	-5.018	-4.538
μ_3	-2.602	-3.281	-2.602	-1.943
ϕ_1	4.995	2.789	4.882	7.952
ϕ_2	2.186	1.064	2.081	3.854
ϕ_3	1.209	0.525	1.157	2.201
σ_1^2	0.391	0.267	0.381	0.570
σ_2^2	0.698	0.438	0.668	1.163
σ_3^2	0.215	0.124	0.199	0.407
CO range	0.647	0.380	0.614	1.103
NO range	1.497	0.772	1.405	2.733
NO ₂ range	1.334	0.706	1.236	2.473

Coregionalization matrix

Posterior Median with the associate 95% credible interval (in brackets) of the elements of the coregionalization matrix and the correlation matrix for each location s .

Y_1	Y_2	Y_3
0.3812	0.1108	0.1085
(0.27;0.57)	(0.01;0.24)	(0.06;0.20)
	0.7110	0.2354
	(0.47;1.22)	(0.14;0.42)
		0.3000
		(0.21;0.50)

Correlations

Y_1	Y_2	Y_3
1	0.2134 (0.03;0.41)	0.3223 (0.17;0.49)
	1	0.520 (0.31;0.69)
		1

Prediction of NO₂

Prediction of NO₂ based on three different models.

(i) Independent model for NO₂					
Site	Mean	2.50%	Median	97.50%	Observed
1	-4.869	-5.986	-4.839	-3.802	-4.342
2	-4.624	-5.082	-4.632	-4.127	-4.585
3	-4.294	-4.679	-4.294	-3.896	-4.100
(ii) Model for NO₂ conditioned on CO					
1	-4.722	-5.712	-4.733	-3.73	-4.342
2	-4.7	-5.106	-4.702	-4.301	-4.585
3	-4.132	-4.471	-4.131	-3.794	-4.100
(iii) Model for NO₂ conditioned on CO and NO					
1	-4.5	-5.313	-4.508	-3.679	-4.342
2	-4.585	-4.964	-4.587	-4.22	-4.585
3	-3.966	-4.26	-3.964	-3.653	-4.100

small

Other Approaches

- ▶ Moving average or kernel convolution of a process:

$$Y_j(\mathbf{s}) = \int k_j(\mathbf{u})Z(\mathbf{s} + \mathbf{u})d\mathbf{u} = \int k_j(\mathbf{s} - \mathbf{s}')Z(\mathbf{s}')ds'$$

where $Z(\mathbf{s})$ is a univariate spatial process and k_j are kernel functions, $j = 1, 2, \dots, p$. Yields the cross covariance

$$C_{ij}(\mathbf{s} - \mathbf{s}') = \int \int k_i(\mathbf{s} - \mathbf{s}' + \mathbf{u})k_j(\mathbf{u}')\rho(\mathbf{u} - \mathbf{u}')d\mathbf{u}d\mathbf{u}'$$

- ▶ Convolution of Covariance Functions: Suppose C_1, C_2, \dots, C_p are valid covariance functions. Define

$C_{ij}(\mathbf{s}) = \int C_i(\mathbf{s} - \mathbf{t})C_j(\mathbf{t})d\mathbf{t}$. Then the $p \times p$ matrix $C(\mathbf{s}) = \{C_{ij}(\mathbf{s})\}$ is a valid cross covariance function

Multivariate Areal Data Examples

- ▶ Cancer counts for areal units for several different types of cancers
- ▶ Employment rates by *sectors* for a set of areal units
- ▶ Individual level bivariate data within units, e.g., height adjusted for age (HAZ) and weight adjusted for age (WAZ) with areal unit level spatial effects for each outcome
- ▶ Spatially varying coefficient models with coefficients at areal scale because covariates are at areal scale

Multivariate Areal Data Models

- ▶ Now areal units (e.g., counties) instead of points
- ▶ Need to model dependence within and across units
- ▶ As in univariate case, use spatial random effects ϕ_{ji} , where again $i = 1, \dots, n$ indexes region but now $j = 1, \dots, p$ indexes variables (e.g., cancer type) within region
- ▶ Suppose we observe $\mathbf{Y}_i = (Y_{1i}, Y_{2i}, \dots, Y_{pi})$, Then

$$g(E(Y_{ji})) = \mathbf{x}_{ji}^T \boldsymbol{\beta}_j + \phi_{ji} ,$$

with $\boldsymbol{\phi}_i = (\phi_{1i}, \dots, \phi_{pi})$ and $\boldsymbol{\phi} = (\boldsymbol{\phi}_1, \dots, \boldsymbol{\phi}_n)$.

- ▶ Link function g useful for modeling rates (e.g., Poisson disease mapping).
- ▶ Multivariate CAR (MCAR) model for the ϕ_{ji}

Some models

- ▶ Illustrate with $p = 2$
- ▶ A disease mapping example: Y_{1i}, Y_{2i} are counts for diseases 1 and 2 in unit i

$$Y_{ji} \sim Po(\lambda_{ji}), \quad j = 1, 2,$$

$$\lambda_{ji} = E_{ji}\eta_{ji}$$

$$\log\eta_{ji} = \mathbf{X}_{ji}^T \boldsymbol{\beta}_j + \phi_{ji}$$

- ▶ Bivariate CAR model for $\{\phi_{1i}, \phi_{2i}\}$
- ▶ Height and weight example:

$$\mathbf{Y}_{ir} = \begin{pmatrix} HAZ_{ir} \\ WAZ_{ir} \end{pmatrix} = \mathbf{X}_{ir} \begin{pmatrix} \boldsymbol{\beta}^{(H)} \\ \boldsymbol{\beta}^{(W)} \end{pmatrix} + \begin{pmatrix} \phi_i^{(H)} \\ \phi_i^{(W)} \end{pmatrix} + \begin{pmatrix} \epsilon_{ir}^{(H)} \\ \epsilon_{ir}^{(W)} \end{pmatrix}$$

- ▶ Bivariate CAR model for $\{\phi_i^{(H)}, \phi_i^{(W)}\}$

Multivariate CAR (MCAR) models

- ▶ Again, local or neighbor idea, conditioning, CAR
- ▶ Approach 1: multivariate CAR (MCAR) in the form $p(\phi_i | \phi_j, j \neq i)$ with

$$p(\phi_i | \phi_{j \neq i}, \Sigma_i) = N \left(\sum_j B_{ij} \phi_j, \Sigma_i \right), \quad i = 1, \dots, n$$

- ▶ As earlier, Brook's Lemma yields $p(\phi)$, improper, etc.
- ▶ Simplification: $B_{ij} = b_{ij} I$, $b_{ij} = w_{ij} / w_{i+}$, $\Sigma_i = \left(\frac{1}{w_{i+}} \right) \Sigma$
- ▶ To make proper, add ρ or perhaps ρ_j , $j = 1, \dots, p$

cont.

- ▶ A coregionalization approach (straightforward)
- ▶ With say, $p = 2$, write

$$\begin{pmatrix} \phi_{1i} \\ \phi_{2i} \end{pmatrix} = A \begin{pmatrix} \eta_{1i} \\ \eta_{2i} \end{pmatrix}$$

- ▶ $\eta_{1i} \sim \text{CAR}(\tau_1)$, $\eta_{2i} \sim \text{CAR}(\tau_2)$
- ▶ η_{1i} , η_{2i} independent